

Source Coding with Common Reconstruction and Action-dependent Side Information

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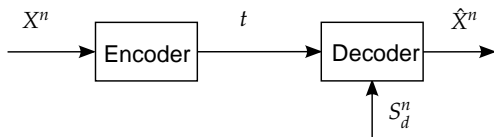
FeedNetback Junior Workshop, 16 September 2010

Outline

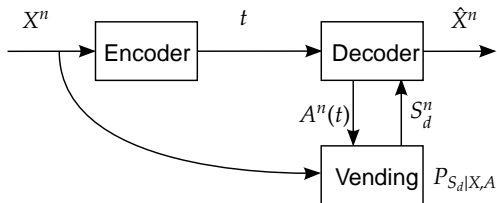
- 1 Motivation and Related Work
- 2 Main Problem
 - Main Result
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Related Work: Source Coding with Side Information

- Source coding with side information at the decoder [Wyner and Ziv '76]



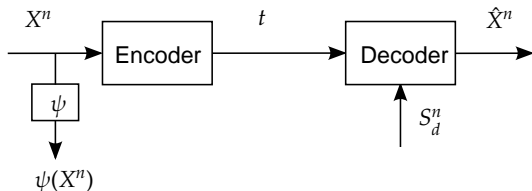
- Source coding with *action-dependent side information* “Vending machine” [Weissman and Permuter '09]



⇒ Decoder can adjust the quality of SI.

Related Work: Source Coding with Side Information

- Lossy source coding \Rightarrow distortion constraint
- What if the encoder wants to know the decoder reconstruction as well? \Rightarrow **Common Reconstruction (CR) constraint** [Steinberg '09]



- $\Rightarrow \lim_{n \rightarrow \infty} \Pr(\psi(X^n) \neq \hat{X}^n) = 0$
- \Rightarrow Medical consultation (MRI results) [Steinberg '09]
- \Rightarrow Both sender and receiver share common knowledge of receiver's reconstruction, i.e., \hat{X}^n .

Our Contribution

- Combining the action-dependent SI and CR constraint for the source coding problem.

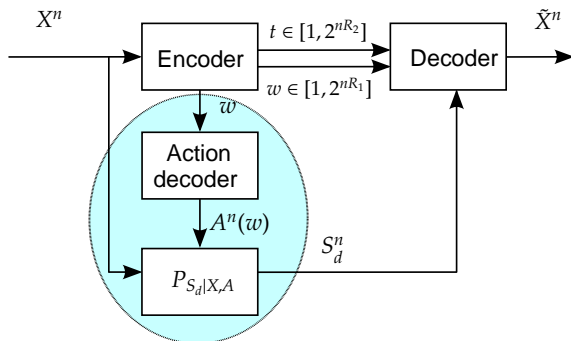
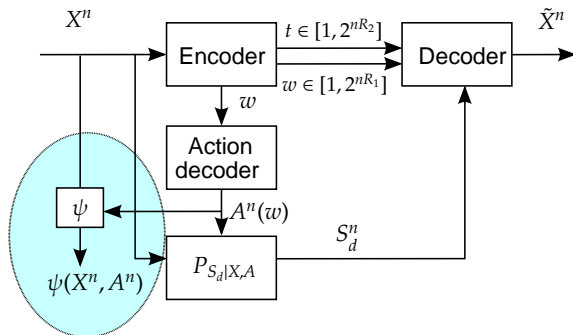


Figure: Action-dependent SI where action is chosen at the encoder and depends on a rate-limited link

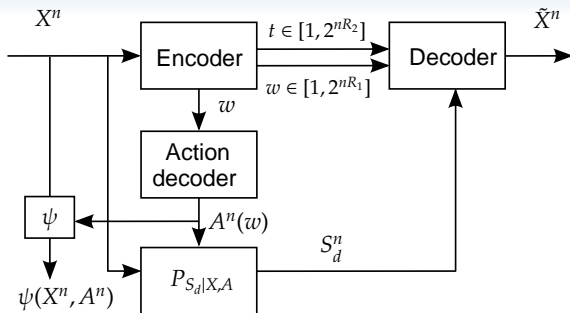
Our Contribution

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- Active control:* Action-dependent SI
- Passive control:* CR constraint
- Potential application in networked control

Problem Formulation



- Encoder: $f^{(n)} : \mathcal{X}^n \rightarrow \mathcal{W}^{(n)} \times \mathcal{T}^{(n)}$, $|\mathcal{W}^{(n)}| = 2^{nR_1}$, $|\mathcal{T}^{(n)}| = 2^{nR_2}$
- Decoder: $g^{(n)} : \mathcal{W}^{(n)} \times \mathcal{T}^{(n)} \times \mathcal{S}_d^n \rightarrow \tilde{\mathcal{X}}^n$
- CR mapping: $\psi^{(n)} : \mathcal{X}^n \times \mathcal{A}^n \rightarrow \hat{\mathcal{X}}^n$, $\hat{\mathcal{X}}^n = \tilde{\mathcal{X}}^n$

Goal: To find the rate region subject to

$$E[d(X^n, \tilde{X}^n)] \leq D, \quad E[\Lambda(A^n)] \leq C, \quad \lim_{n \rightarrow \infty} \Pr(\psi^{(n)}(X^n, A^n) \neq \tilde{X}^n) = 0.$$

Rate Region

Definition: Rate Region

Let $\mathcal{P}(D, C)$ denote the set of all joint pmfs p which have the form

$$P_X(x)P_{A|X}(a|x)P_{S_d|X,A}(s_d|x, a)P_{\hat{X}|X,A}(\hat{x}|x, a),$$

and satisfy

$$E[d(X, \hat{X})] \leq D, \text{ and } E[\Lambda(A)] \leq C.$$

For each $p \in \mathcal{P}(D, C)$, define

$$\mathcal{R}^*(D, C, p) \triangleq \{(R_1, R_2) : R_1, R_2 \geq 0, R_1 + R_2 \geq I(X; \hat{X}, A) - I(\hat{X}; S_d|A)\},$$

and

$$\mathcal{R}^*(D, C) \triangleq \bigcup_{p \in \mathcal{P}(D, C)} \mathcal{R}^*(D, C, p).$$

Rate Region

Theorem: Optimal Rate Region

The optimal rate region containing all achievable rate pairs for the memoryless source with action-dependent side information available at the decoder is given by

$$\mathcal{R}(D, C) = \mathcal{R}^*(D, C).$$

Remark:

⇒ No S_d in the distortion constraint $E[d(X, \hat{X})] \leq D$ (different from that in Wyner-Ziv!)

Sum-rate Distortion and Cost Function

Corollary: Sum-rate distortion and cost function

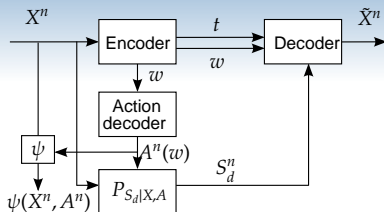
The sum-rate distortion and cost function for the memoryless source with CR and action-dependent SI available at the decoder is given by

$$\begin{aligned} R_{ac,cr}(D, C) &= \min_{p \in \mathcal{P}(D, C)} [I(X; \hat{X}, A) - I(\hat{X}; S_d | A)] \\ &\stackrel{(*)}{=} \min_{p \in \mathcal{P}(D, C)} [I(X; A) + I(\hat{X}; X | A, S_d)], \end{aligned}$$

(*) follows from the Markov chain $\hat{X} - (X, A) - S_d$.

Outline of the Proof

The proof follows from arguments in [Wyner and Ziv '76], [Weissman and Permuter '09], and [Steinberg '09].



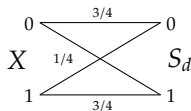
- **Achievability:** using a random coding argument
 - **Codebook generation:** $a^n(w) \sim P_A$, and $\hat{x}^n(t, v, w) \sim P_{\hat{X}|A}$
 - **Encoding:** given the source, find (t, v, w) s.t. \hat{x}^n, x^n , and a^n are jointly typical, then transmit t, w to the decoder and w to the action decoder. Also, put out $\hat{x}^n(t, v, w)$ as CR.
 - **Decoding:** put out $\tilde{x}^n = \hat{x}^n$ which is jointly typical with a^n and s_d^n
 \Rightarrow Typicality guarantees the distortion, cost and CR constraints.
- **Converse:** standard information-theoretic argument

Example: To observe, or not to observe S_d

- Comparing $R_{ac,cr}(D, C)$ to $R_{ac}(D, C)$ (without CR constraint)

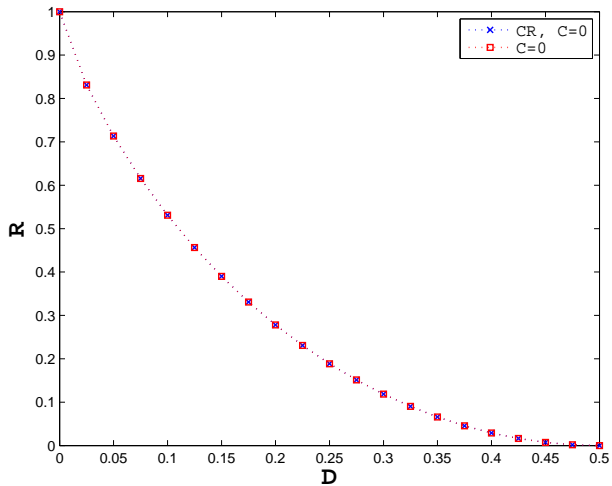
- Consider the binary sets $\mathcal{X} = \hat{\mathcal{X}} = \mathcal{S}_d = \mathcal{A} = \{0, 1\}$

- $X \sim \text{Bern}(1/2)$
- $A = 1 \Rightarrow$ observe S_d
- $A = 0 \Rightarrow$ not observing it

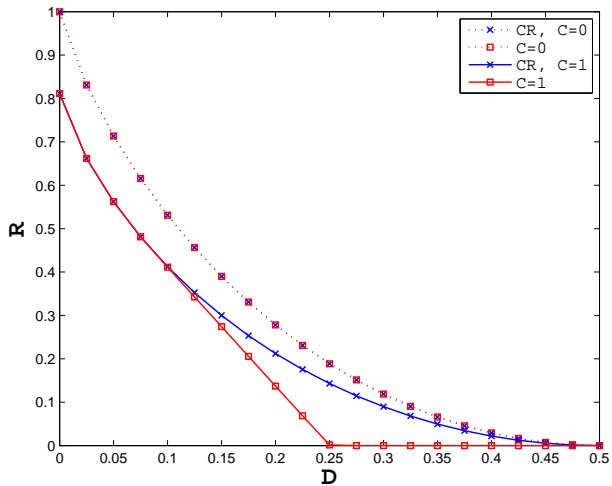


- Assume that an observation has a unit cost, i.e., $\Lambda(A) = A$ and $E[\Lambda(A)] = P_A(1) = C$
- Consider the Hamming distance as a distortion measure

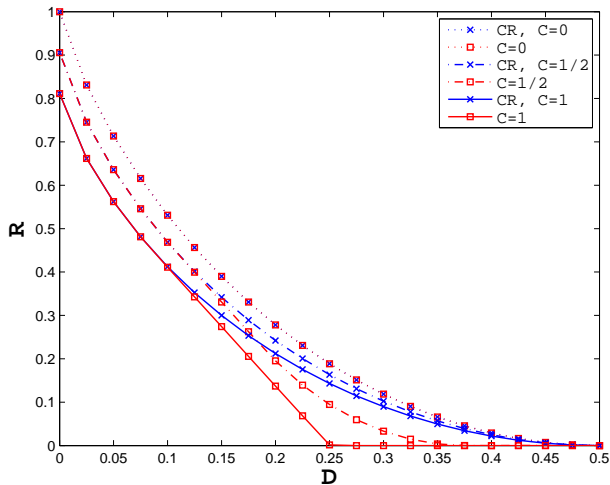
Rate-Distortion Curves



Rate-Distortion Curves



Rate-Distortion Curves



- Performance loss due to CR constraint

Summary

- Source coding problem with action-dependent SI and CR (extension of Wyner-Ziv)
- The rate region is characterized (depending only on the sum rate constraint)
- Potential application in networked control

Thank you for your attention!

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References



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